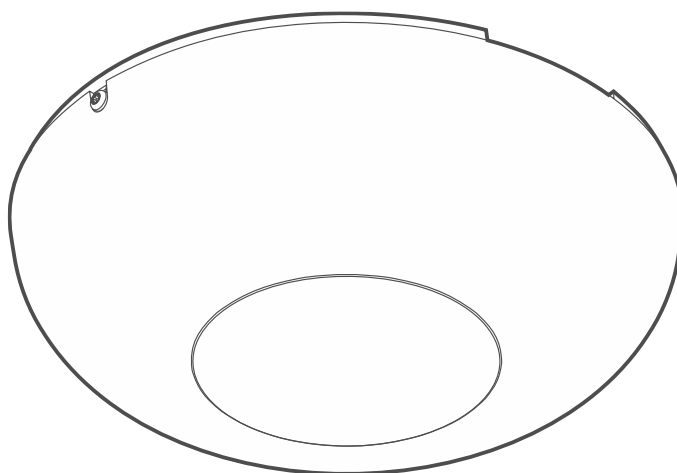


Ceiling PIR motion detector
(surface mount)

SLIM-S-PIR

Firmware version 3.00

EN



slim-s-pir_en 04/26

IMPORTANT

The device should be installed by qualified personnel.

Prior to installation, please read carefully this manual.

Changes, modifications or repairs not authorized by the manufacturer shall void your rights under the warranty.

Description of symbols on the device:



Direct current (DC).



The device meets the requirements of the applicable EU directives.



The device is designed for indoor installation.



The device must not be disposed of with other municipal waste. It should be disposed of in accordance with the existing rules for environment protection (the device was placed on the market after 13 August 2005).

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The declaration of conformity may be consulted at www.satel.pl/ce

Signs in this manual



Caution – information on the safety of users, devices, etc.



Note – suggestion or additional information.

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The SLIM-S-PIR ceiling detector uses infrared to detect motion. It is designed for mounting on the surface of the ceiling. This manual applies to the detector with electronics version D.

1. Features

- Motion detection using passive infrared sensor (PIR).
- Maximum coverage area (see Fig. 19):
 - ø 6 m / 28 m² – mounted at 2.4 m,
 - ø 10 m / 79 m² – mounted at 3.5 m.
- Digital motion detection algorithm.
- Digital temperature compensation.
- Adjustable detection sensitivity.
- Built-in end-of-line resistors (2EOL: 2 x 1.1 kΩ).
- LED indicator:
 - selectable color for alarm indication (7 colors available).
 - indicator enabled / disabled remotely.
- Supervision of motion detection system.
- Powered by 12 VDC (±15%).
- Supply voltage control.
- Tamper protection against enclosure opening and removal from mounting surface.
- Mounted on the surface of the ceiling.

2. Description

The detector will report alarm when the infrared sensor (PIR) detects motion.

Tamper protection

Enclosure opening / removal of the detector from the mounting surface results in activating the tamper output. The output will remain activated until the end of tamper.

Supervision features

In the event of the voltage drop below 9 V (±5%) for more than 2 seconds or the motion detection system failure, the detector will indicate a trouble. The trouble is indicated by activating the alarm output and turning on the LED indicator. The signaling continues for the duration of the trouble.

LED indicator

The LED indicator indicates:

- warm-up – flashing red for about 30 seconds,
- alarm – ON for 2 seconds (default color: blue),
- trouble – ON for the duration of the trouble (the same color of lighting as in the case of alarm).

You can change the color to be used to indicate alarm / trouble (see *Configuring the detector using the buttons* p. 8).

Enabling the LED indicator using the DIP-switch

If you enable the LED indicator using the switch (set the 8 switch in ON position – Fig. 6), the indicator will indicate events but it will be impossible to enable / disable the indicator

remotely. If you disable the LED indicator using the switch (Fig. 7), it will be possible to enable / disable the indicator remotely.

Enabling / disabling the LED indicator remotely

The LED terminal is provided to allow the LED indicator to be controlled remotely. The LED indicator is enabled when the terminal is connected to common ground. The LED indicator is disabled when the terminal is disconnected from common ground.

You can connect to the terminal an OC type alarm control panel output programmed e.g. as:

- INTEGRA / INTEGRA Plus: *Zone test status* or *BI switch*,
- PERFECTA / VERSA: *Controlled*.

3. Electronics module



Do not remove the electronics board from the plastic cover to avoid damage to the components on the board.

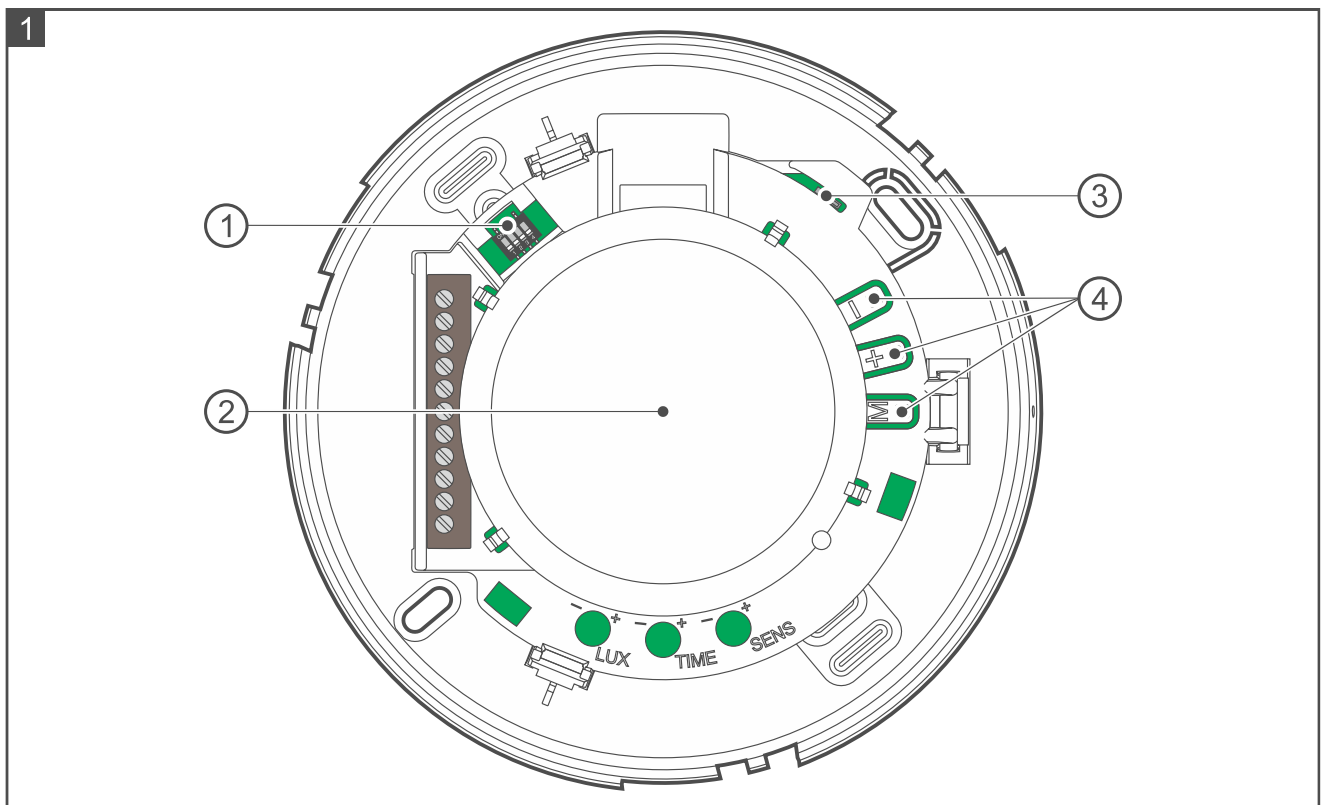
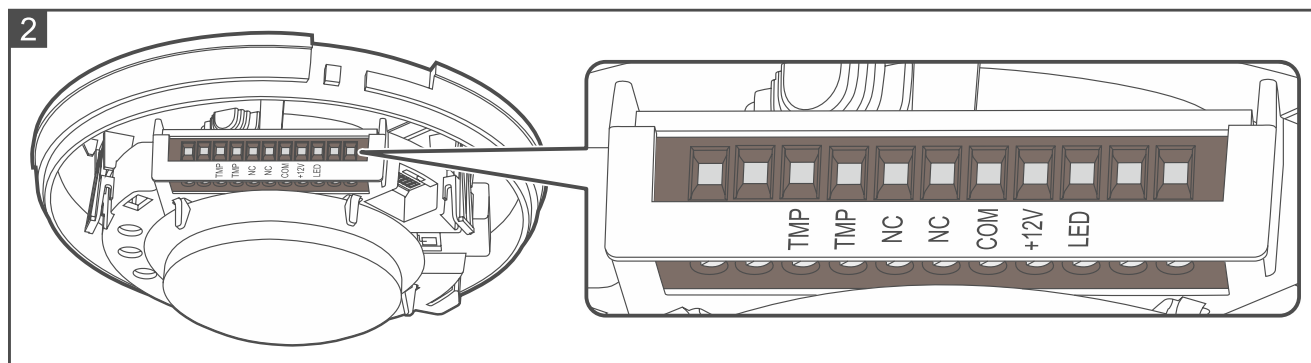


Figure 1 shows the inside of the detector after opening the enclosure.

- ① DIP-switches used for configuring the detector (see *DIP-switches* p. 4).
- ② lens.
- ③ tamper switch activated by cover removal.
- ④ buttons used for configuring the detector (see *Configuring the detector using the buttons* p. 8).

The PIR sensor (dual element pyrosensor) and the LED indicator are under the lens. The tamper switch activated by removing the detector from the surface is on the other side of the electronics module.

Terminals



TMP - tamper output (NC).

NC - alarm output (NC relay).

COM - common ground.

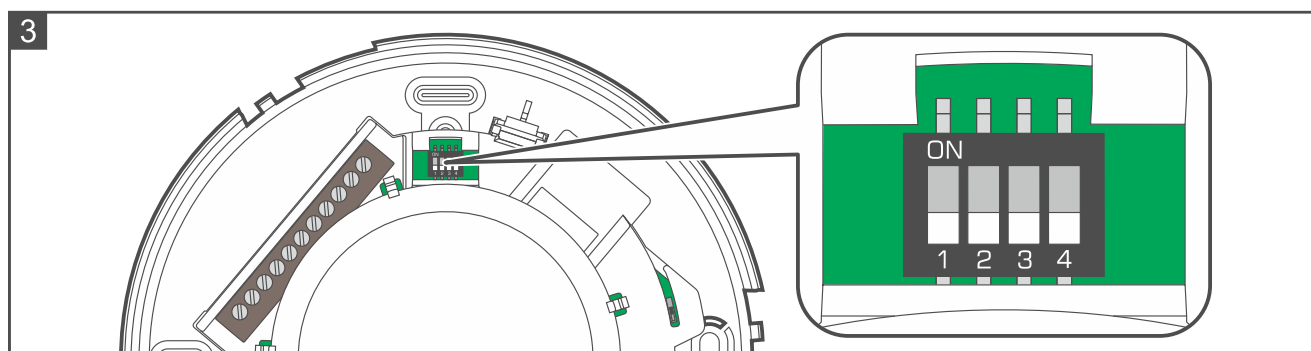
+12V - power input.

LED - enabling / disabling the LED.

DIP-switches

Using the DIP-switches, you can:

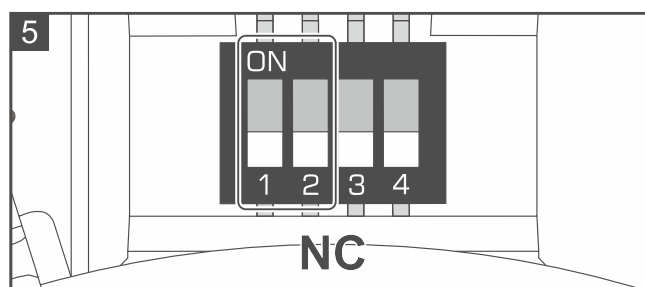
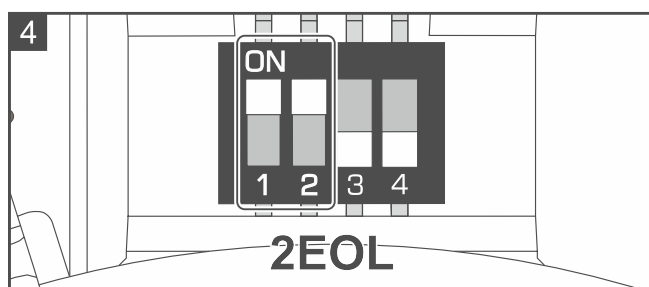
- configure the detector outputs – switches 1 and 2 (Fig. 4 and 5),
- enable / disable the LED indicator – switch 4 (Fig. 6 and 7).



Configuring the detector outputs

Available settings are shown in the figures:

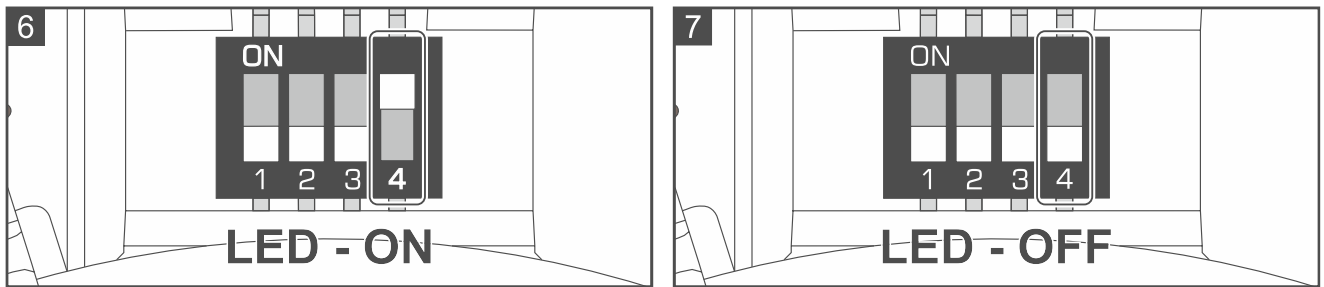
- 4 – built-in resistors are used – connect the detector outputs as in Fig. 18,
- 5 – built-in resistors are not used – connect the detector outputs as in Fig. 17.



Enabling / disabling the LED indicator

Available settings are shown in the figures:

- 6 – LED indicator is enabled,
- 7 – LED indicator is disabled.

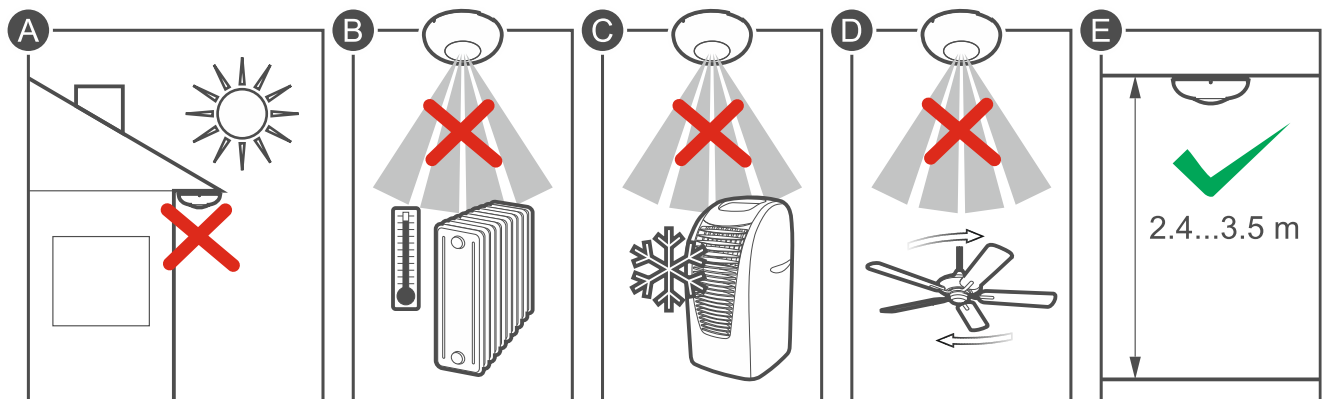


4. Installation



Disconnect power before making any electrical connections.

Tips for installation



- The detector should be installed indoors, in spaces with normal air humidity.
- Do not install the detector outdoors (A).
- Do not point the detector towards heat sources (B), air conditioners (C) or fans (D).
- No object should obstruct the detector's field of view.
- Install the detector on the surface of the ceiling, at a height of 2.4...3.5 m (E).



If you want to install the detector at a height other than the recommended, make sure the coverage area of the detector mounted at that height is optimal. The maximum coverage area of the detector mounted at a height of 4.5 m is $\varnothing$ 8 m [50 m²].

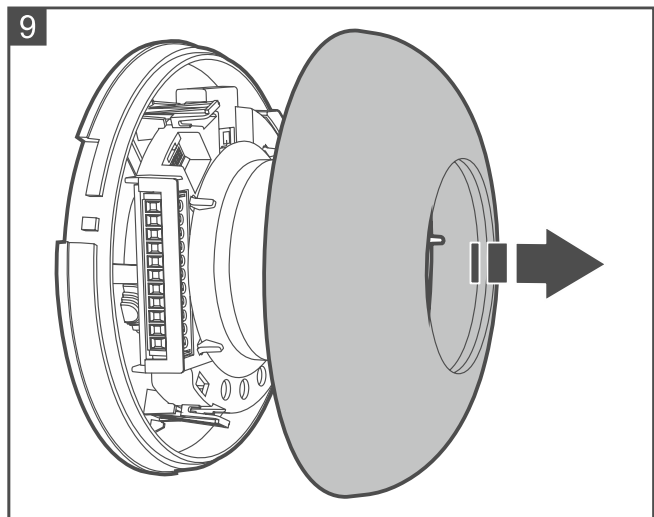
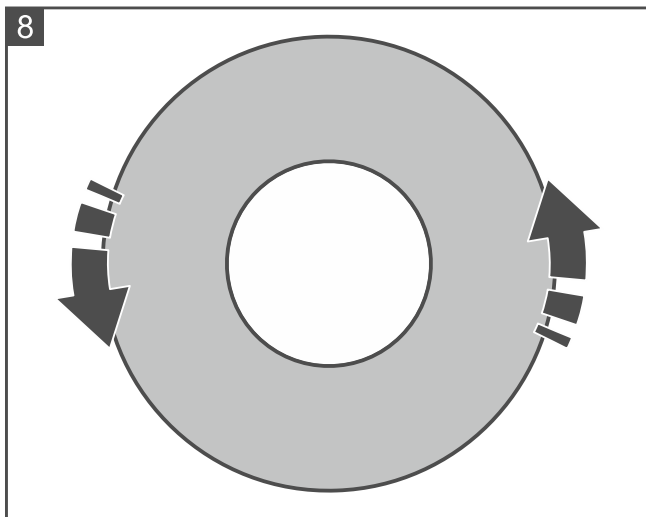
Mounting

1. Turn the enclosure cover counter-clockwise (Fig. 8) and remove it (Fig. 9).
2. Configure the detector using the DIP-switches (see *DIP-switches* p. 4).
3. Place the enclosure base against the ceiling and mark the location of the mounting holes (Fig. 10).

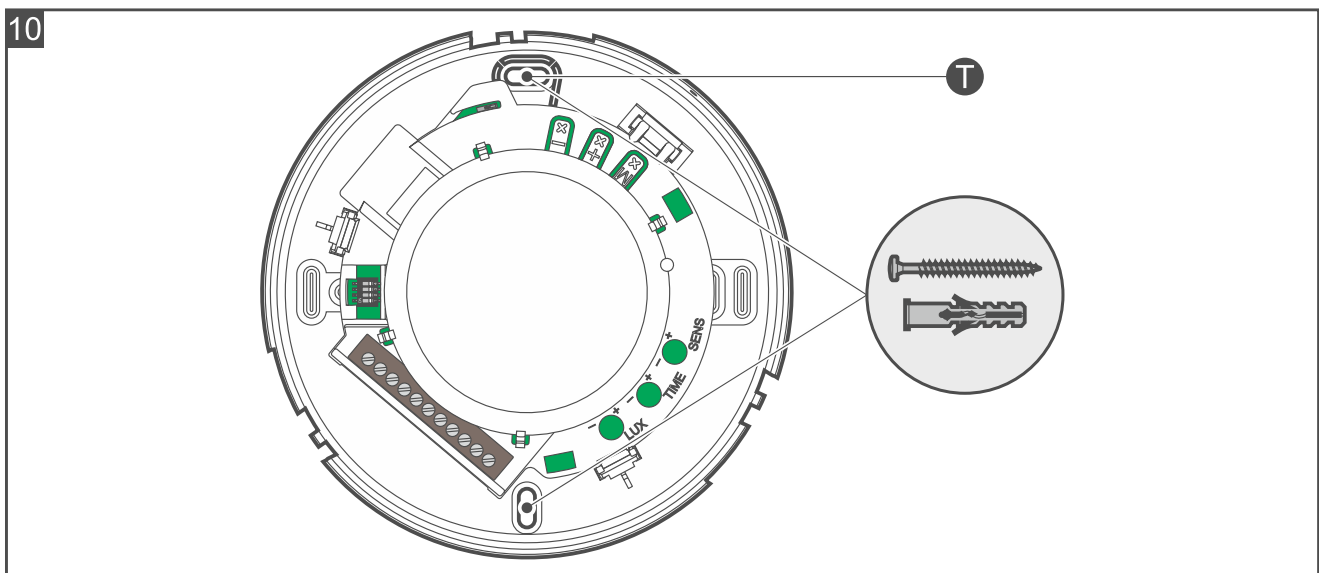


In order for the detector to detect removal from the surface, fasten the screw in the place marked as **T** in Fig. 10.

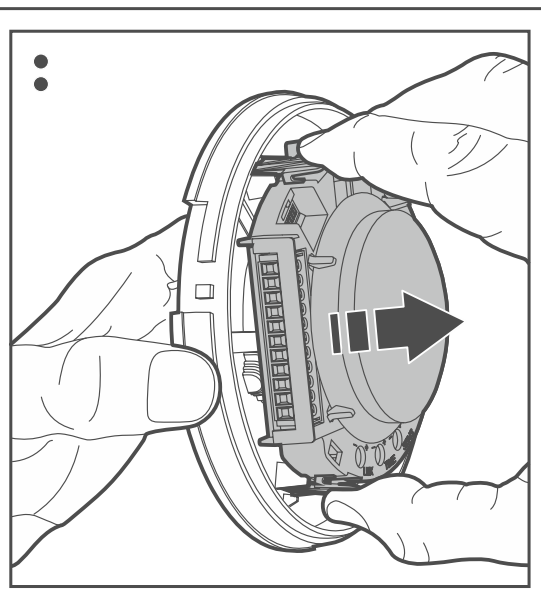
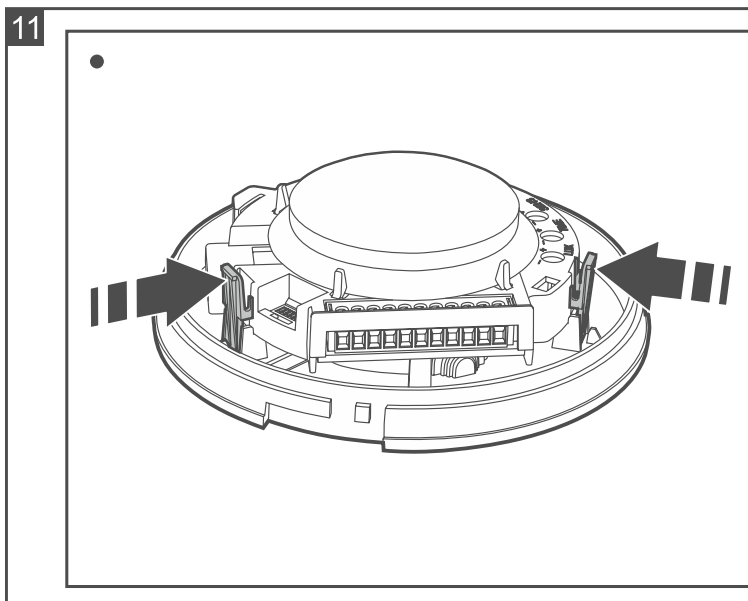
Figure 13 shows the places where additional mounting holes can be made. They are visible after you lift up the electronics module (see Fig. 11).



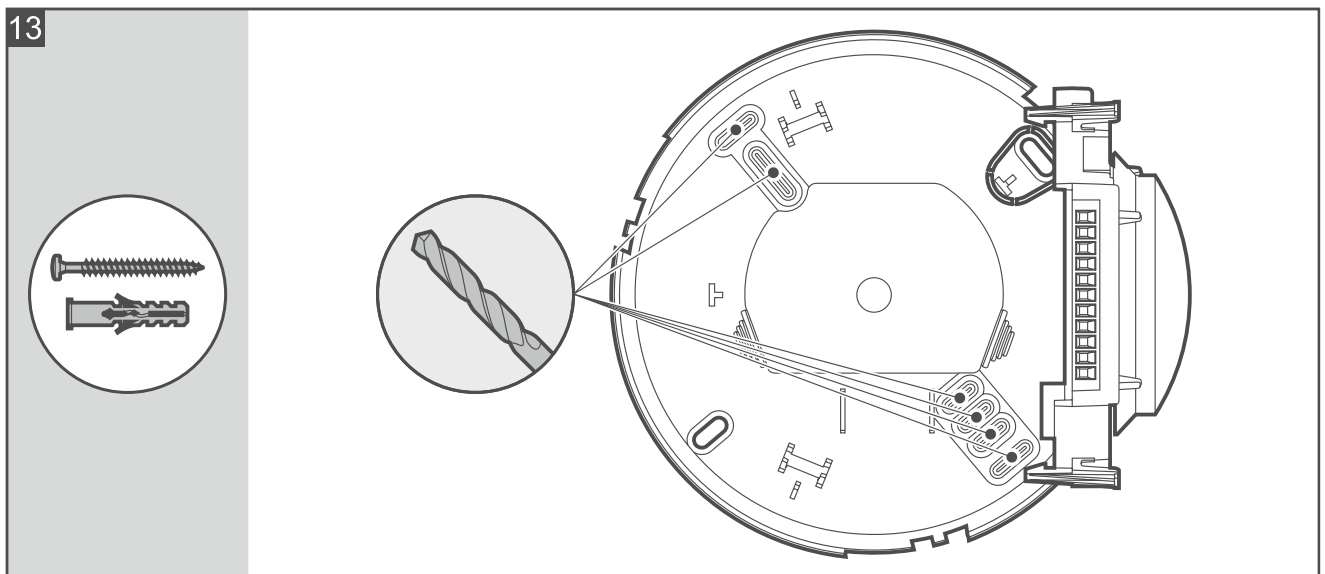
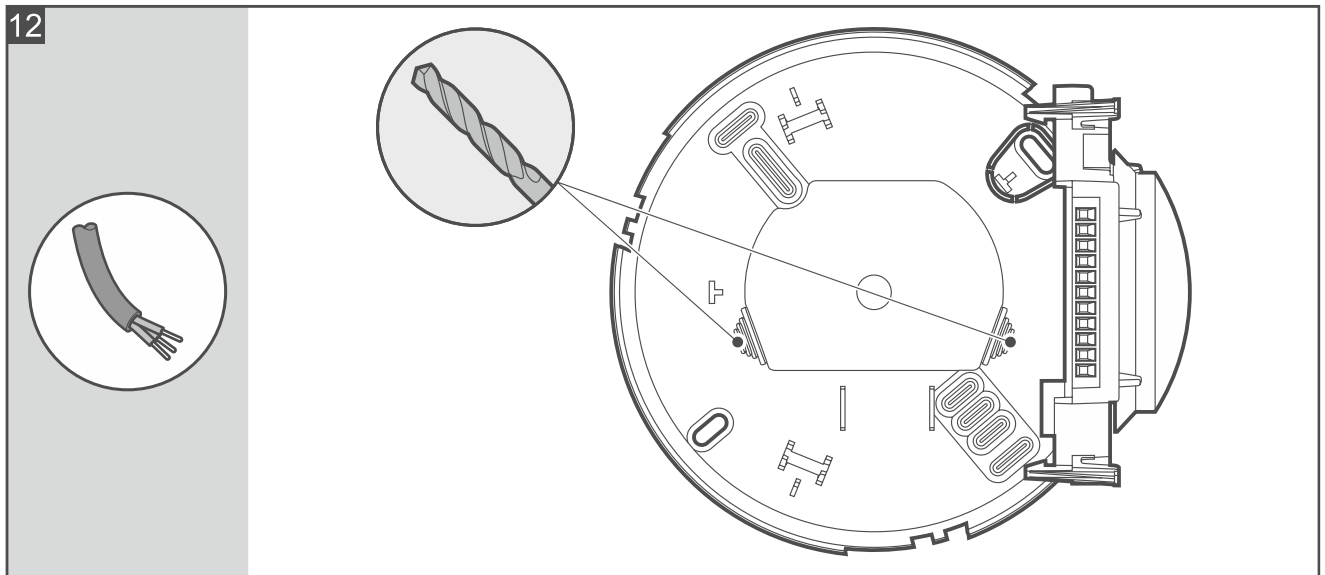
4. Drill the holes in the ceiling for wall plugs (anchors). The wall plugs provided with the detector are intended for concrete or brick. For other types of surface (drywall, styrofoam), use other appropriately selected wall plugs.



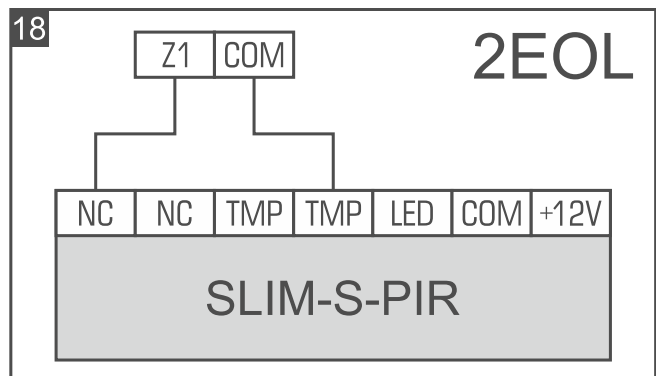
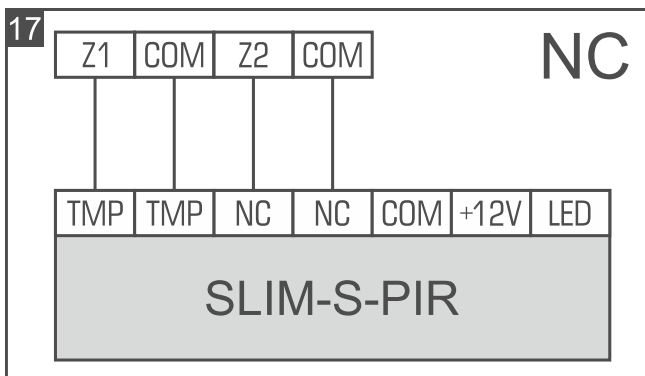
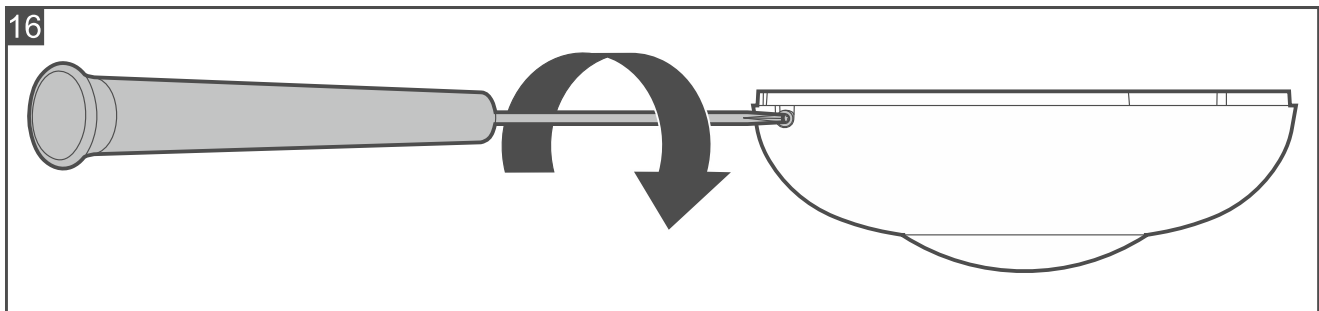
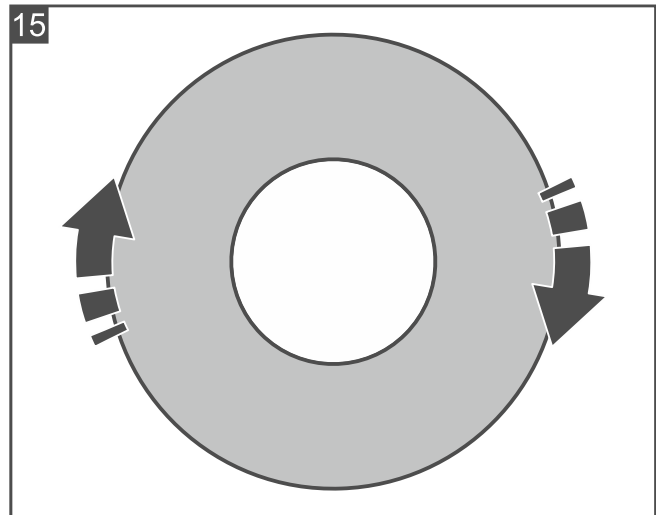
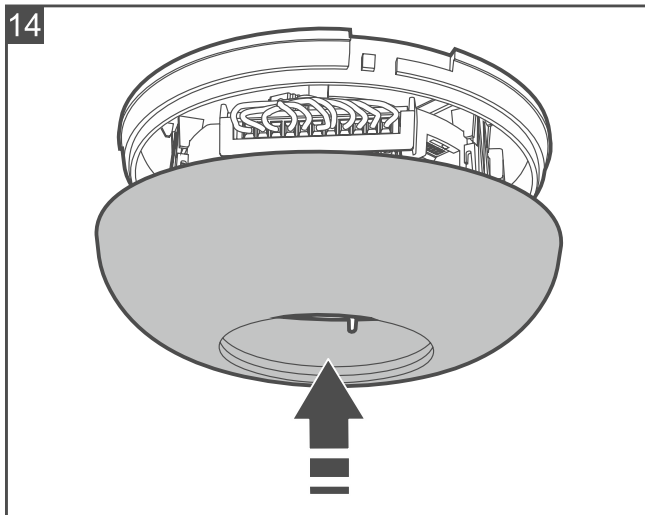
5. Press the catches and lift up the electronics module (Fig. 11).



6. Make the opening for a cable in the enclosure base (Fig. 12).
7. Run the cable inside the detector enclosure.
8. Secure the enclosure base to the ceiling with screws (Fig. 10 and 13).



9. Screw the wires to the detector terminals.
10. Press the electronics module down onto the base to lock it in place.
11. Power on the detector. The LED indicator will be flashing red for 30 seconds to indicate the detector warm-up.
12. Once the LED indicator stops flashing, configure the remaining detector settings (see *Configuring the detector using the buttons* p. 8).
13. Place the enclosure cover in the base (Fig. 14). Note the position of the cover locking screw holes.
14. Turn the cover clockwise until you feel resistance (Fig. 15).
15. Lock the cover in place with a screw (Fig. 16). The screw is in the bag provided with the detector. Use a Torx T6H screwdriver.



5. Configuring the detector using the buttons

Description of detector buttons

- M** - starting configuration mode / ending configuration mode / running a function / saving changes and exiting a function.
- +** - next function / next value.
- - previous function / previous value.

Starting configuration mode

Press **M** for 3 seconds. The LED indicator will start flashing red.

Configuring the settings

1. Use **+** or **-** to find the function you want to run. The number of flashes of the LED indicator is the function number (see table 1).
2. Press **M** to run the function. The LED indicator will start flashing green. The number of flashes is the currently set value (see table 1).

3. Use **+** or **-** to set a new value.
4. Press **M** to save changes and exit the function. The LED indicator will start flashing red to indicate that you returned to the list of functions.

Function number	Description of function
1	Setting the PIR sensor sensitivity You can program from 1 to 16 (1 - minimum; 16 – maximum). By default: 8 . When the function is running, the LED indicator indicates that the PIR sensor has detected motion: it is ON in red for 2 seconds. This enables the PIR sensor coverage area to be tested for the selected sensitivity.
2	Setting the LED indicator light color for indicating alarm / trouble You can program from 1 to 7 (1-7 – color). By default: 3 (blue). The LED indicator shows the selected color (for 2 seconds).

Table 1

Restoring factory settings

To restore the detector factory settings, press and hold **-** and **+** for 3 seconds in the configuration mode.

Ending configuration mode

Press **M** for 3 seconds.



The configuration mode will be turned off automatically 20 minutes after the last operation performed by the user.

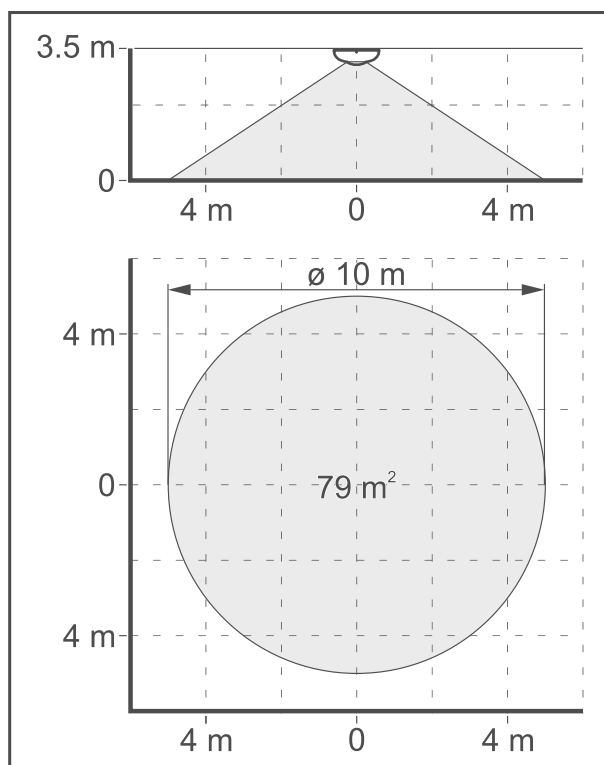
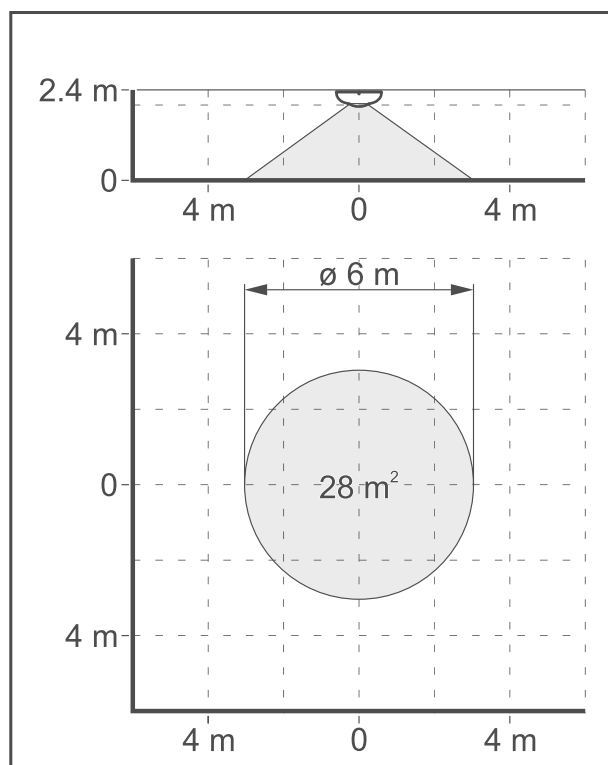
6. Walk test



The LED indicator should be enabled during the walk test (see LED indicator p. 2).

1. Check if moving within the detector coverage area will make the LED indicator turn ON. Figure 19 shows the maximum coverage area of the detector.
2. If necessary, change the sensitivity of the sensor (see *Configuring the detector using the buttons*).

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7. Specifications

Supply voltage	12 VDC $\pm$ 15%
Standby current consumption	11 mA
Maximum current consumption	38 mA
EOL resistors	2 x 1.1 k Ω
Outputs	
alarm (NC relay, resistive load).....	40 mA / 24 VDC
tamper (NC)	100 mA / 30 VDC
Relay contact resistance (alarm output).....	26 Ω
Detectable speed	0.3...3 m/s
Alarm signaling period.....	2 s
Warm-up period	30 s
Recommended installation height	2.4...3.5 m
Maximum coverage area	
mounted at 2.4 m	$\varnothing$ 6 m [28 m²]
mounted at 3.5 m	$\varnothing$ 10 m [79 m²]
Security grade according to EN 50131-2-2	Grade 2
Compliance with standards	EN 50131-1, EN 50131-2-2, EN 50130-4, EN 50130-5
Environmental class according to EN 50130-5	II
Operating temperature range	-10°C...+55°C
Maximum humidity	93 $\pm$ 3%
Dimensions	$\varnothing$ 120 x 37 mm
Weight.....	115 g

5 year warranty from date of manufacture